

MA3514 Exam Solutions
Semester B, 2005-2006

p.1

$$1. \text{ let } y' = u \Rightarrow \frac{d}{dt} \begin{bmatrix} y \\ u \end{bmatrix} = \begin{bmatrix} u \\ -y^2 + u + t \end{bmatrix} \\ = f(t, \begin{bmatrix} y \\ u \end{bmatrix})$$

$$\begin{bmatrix} y_0 \\ u_0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\vec{k}_1 = f(t_0, \begin{bmatrix} y_0 \\ u_0 \end{bmatrix}) = f(0, \begin{bmatrix} 1 \\ 2 \end{bmatrix}) = \begin{bmatrix} 2 \\ -1^2 + 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\vec{k}_2 = f(t_0 + \frac{h}{2}, \begin{bmatrix} y_0 \\ u_0 \end{bmatrix} + \frac{h}{2} \vec{k}_1)$$

$$= f(0.05, \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 0.05 \begin{bmatrix} 2 \\ 1 \end{bmatrix})$$

$$= f(0.05, \begin{bmatrix} 1.1 \\ 2.05 \end{bmatrix}) = \begin{bmatrix} 2.05 \\ -1.1^2 + 2.05 + 0.05 \end{bmatrix}$$

$$= \begin{bmatrix} 2.05 \\ 0.89 \end{bmatrix}$$

$$\begin{bmatrix} y_1 \\ u_1 \end{bmatrix} = \begin{bmatrix} y_0 \\ u_0 \end{bmatrix} + h \vec{k}_2 = \begin{bmatrix} 1.205 \\ 2.089 \end{bmatrix}$$

$$\Rightarrow y(0.1) \approx y_1 = 1.205$$

2. We have Taylor series:

$$y(h) = y(0) + h y'(0^+) + \frac{h^2}{2} y''(0^+) + \dots$$

$$y(-h) = y(0) - h y'(0^-) + \frac{h^2}{2} y''(0^-) + \dots$$

$$p y(h) + y(-h) = (p+1)y(0) + \frac{h^2}{2} [p y''(0^+) + y''(0^-)] + \dots$$

Next, we use the differential equation

at $x=0^+$ and $x=0^-$,

$$\text{thus: } y''(0^-) + q(0^-) y(0) = r(0)$$

$$y''(0^+) + q(0^+) y(0) = r(0)$$

$$\Rightarrow p y(h) + y(-h) = (p+1) y(0)$$

$$+ \frac{h^2}{2} [p r(0) - p q(0^-) y(0)$$

$$+ r(0) - q(0^+) y(0)] + \dots$$

$$\begin{aligned} \therefore p y(h) + y(-h) - (p+1) y(0) &+ \frac{h^2}{2} p q(0^-) y(0) \\ &+ \frac{h^2}{2} q(0^+) y(0) \\ &= \frac{h^2}{2} (p+1) r(0) + \dots \end{aligned}$$

$$\begin{aligned} \Rightarrow: \frac{1}{h^2} \left[\frac{2}{p+1} y(-h) - 2 y(0) + \frac{2p}{p+1} y(h) \right] \\ + \left[\frac{q(0^+)}{p+1} + \frac{p}{p+1} q(0^-) \right] y(0) = r(0) \end{aligned}$$

thus, $ay_{-1} + by_0 + cy_1 = d$

where $a = \frac{2}{(p+1)h^2}$, $b = \frac{-2}{h^2} + \frac{2(10^4) + p \cdot 2(10^4)}{p+1}$

$c = \frac{2p}{(p+1)h^2}$, $d = f(0)$

3. The Crank-Nicolson method is:

$$\frac{1}{\Delta t} [u_j^1 - u_j^0] = \frac{(1 + \alpha_j)}{2(\Delta x)^2} [u_{j-1}^1 - 2u_j^1 + u_{j+1}^1 + u_{j-1}^0 - 2u_j^0 + u_{j+1}^0]$$

Boundary Conditions: $u_0^k = u_4^k = 0$, $\Delta x = \frac{1}{4}$

Initial Conditions: $u_1^0 = \frac{1}{2}$, $u_2^0 = 1$, $u_3^0 = \frac{1}{2}$

For $j=1$:

$$u_1^1 - \frac{1}{2} = \frac{5}{2} [-2u_1^1 + u_2^1 + 0]$$

$$\Rightarrow 6u_1^1 - \frac{5}{2}u_2^1 = \frac{1}{2}$$

For $j=2$:

$$u_2^1 - 1 = 3 [u_1^1 - 2u_2^1 + u_3^1 + (-1)]$$

$$\Rightarrow -3u_1^1 + 7u_2^1 - 3u_3^1 = -2$$

For $j=3$:

$$u_3^1 - \frac{1}{2} = \frac{7}{2} [u_2^1 - 2u_3^1 + 0]$$

$$\Rightarrow: -\frac{7}{2} u_2' + 8 u_3' = \frac{1}{2}$$

$$\Rightarrow \begin{bmatrix} 6 & -\frac{5}{2} & 0 \\ -3 & 7 & -3 \\ 0 & -\frac{7}{2} & 8 \end{bmatrix} \begin{bmatrix} u_1' \\ u_2' \\ u_3' \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ -2 \\ \frac{1}{2} \end{bmatrix}$$

4. For $u_t + a(x) u_x = 0$, we have

$$\begin{aligned} u(x, t + \Delta t) &= u(x, t) + \Delta t \cdot u_t(x, t) + \frac{(\Delta t)^2}{2} u_{tt}(x, t) + \dots \\ &\approx u - \Delta t \cdot a(x) u_x + \frac{(\Delta t)^2}{2} a(x) (a(x) u_x)_x \end{aligned}$$

\Rightarrow : Lax-Wendroff method is

$$\begin{aligned} u_j' &= u_j^0 - \frac{\Delta t a(x_j)}{2 \Delta x} [u_{j+1}^0 - u_{j-1}^0] \\ &\quad + \frac{(\Delta t)^2}{2 (\Delta x)^2} a(x_j) \left[a(x_{j+\frac{1}{2}}) (u_{j+1}^0 - u_j^0) - a(x_{j-\frac{1}{2}}) (u_j^0 - u_{j-1}^0) \right] \end{aligned}$$

Here: $u_j^0 = f(x_j)$, $\Rightarrow u_1^0 = 0.2$, $u_0^0 = 0$, $u_{-1}^0 = 0$

$$a(x) = 1+x \Rightarrow a(x_0) = 1, a(x_{0+\frac{1}{2}}) = 1.1$$

$$a(x_{0-\frac{1}{2}}) = 0.9$$

$$\Rightarrow u_0' = 0 - \frac{1}{4} \times 0.2 + \frac{1}{8} [1.1 \times 0.2 - 0.9 \times 0]$$

$$= -0.0225$$

5. At (x_i, y_j) , $x_i = ih$, $y_j = jh$

We have:

$$u_{i-1,j} + u_{i+1,j} + u_{i,j-1} + u_{i,j+1} - 4u_{ij} + h^2 \cdot x_i u_{ij} = h^2 y_j$$

thus:

at (x_1, y_1) :

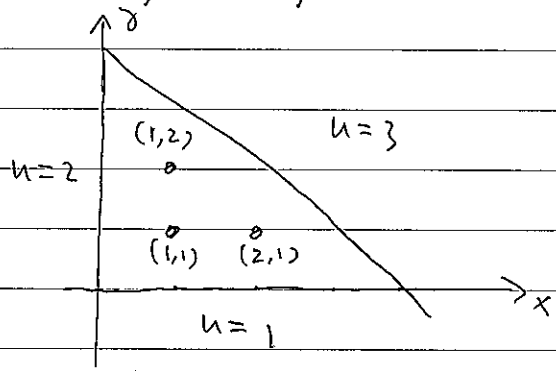
$$1 + 2 - 4u_{11} + u_{21} + u_{12} + \frac{1}{64} u_{11} = \frac{1}{64}$$

at (x_2, y_1) :

$$1 + 3 + 3 - 4u_{21} + u_{11} + \frac{1}{32} u_{21} = \frac{1}{64}$$

at (x_1, y_2) :

$$2 + 3 + 3 - 4u_{12} + u_{11} + \frac{1}{64} u_{12} = \frac{1}{32}$$



$$\Rightarrow: \begin{bmatrix} -\frac{255}{64} & 1 & 1 \\ 1 & -\frac{127}{32} & 0 \\ 1 & 0 & -\frac{255}{64} \end{bmatrix} \begin{bmatrix} u_{11} \\ u_{21} \\ u_{12} \end{bmatrix} = \begin{bmatrix} -\frac{191}{64} \\ \frac{447}{64} \\ -\frac{255}{32} \end{bmatrix}$$

$$6. (a) \frac{1}{\Delta t} \left[E_j^{k+\frac{1}{2}} - E_j^{k-\frac{1}{2}} \right] = -\frac{1}{\epsilon} \cdot \frac{1}{\Delta z} \left[H_{j+\frac{1}{2}}^k - H_{j-\frac{1}{2}}^k \right]$$

$$\frac{1}{\Delta t} \left[H_{j+\frac{1}{2}}^{k+1} - H_{j+\frac{1}{2}}^k \right] = -\frac{1}{\mu} \cdot \frac{1}{\Delta z} \left[E_{j+1}^{k+\frac{1}{2}} - E_j^{k+\frac{1}{2}} \right]$$

(b) Insert the special solutions into the above

numerical scheme, we get:

$$\frac{E_x \left(\sqrt{\rho} - \frac{1}{\sqrt{\rho}} \right)}{\Delta t} = -\frac{1}{\epsilon} \cdot \frac{H_x}{\Delta z} \left[e^{i \frac{\beta \Delta z}{2}} - e^{-i \frac{\beta \Delta z}{2}} \right]$$

$$\frac{H_x}{\Delta t} \left[\sqrt{\rho} - \frac{1}{\sqrt{\rho}} \right] = -\frac{1}{\mu} \cdot \frac{E_x}{\Delta z} \left[e^{i \frac{\beta \Delta z}{2}} - e^{-i \frac{\beta \Delta z}{2}} \right]$$

$$\Rightarrow \frac{H_x}{\epsilon E_x} = \frac{1}{\mu} \frac{E_x}{H_x} = \frac{1}{\sqrt{\epsilon \mu}} = c$$

$$\Rightarrow: \sqrt{\rho} - \frac{1}{\sqrt{\rho}} = -\frac{c \cdot \Delta t}{\Delta z} \left[e^{i \frac{\beta \cdot \Delta z}{2}} - e^{-i \frac{\beta \cdot \Delta z}{2}} \right]$$

$$= -\frac{c \cdot \Delta t}{\Delta z} \cdot 2i \sin \left(\frac{\beta \cdot \Delta z}{2} \right) = -2 \tau i$$

where $\tau = c \cdot \frac{\Delta t}{\Delta z} \sin \left(\frac{\beta \cdot \Delta z}{2} \right)$

$$\Rightarrow \sqrt{\rho} - \frac{1}{\sqrt{\rho}} = -2 \tau i \Rightarrow \rho + 2i\tau \sqrt{\rho} - 1 = 0$$

$$\Rightarrow \sqrt{\rho} = -i\tau \pm \sqrt{-\tau^2 + 1}$$

if: $c \cdot \frac{\Delta t}{\Delta z} \ll 1$ then $|\tau| \ll 1$

$$\Rightarrow |\sqrt{\rho}| = 1 \Rightarrow |\rho| = 1$$

\Rightarrow stable

If $C \cdot \frac{\Delta t}{\Delta z} > 1$ then, we can choose

β such that $|\tau| > 1$, then

one of the two solutions of $\sqrt{\rho}$
satisfies $|\sqrt{\rho}| > 1$ or $|\rho| > 1$
 \Rightarrow unstable.

In conclusion, the numerical method

is stable if $C \cdot \frac{\Delta t}{\Delta z} \leq 1$

is unstable if $C \cdot \frac{\Delta t}{\Delta z} > 1$

where $C = \frac{1}{\sqrt{\epsilon \mu}}$.